

## Replacement Page 1, 1st Paragraph

### BACKGROUND OF THE INVENTION

The invention relates to a compression-resistant drive chain for an adjusting device having several chain links connected to one another in a pivotable way by connecting plates, which chain links are comprised of at least two swivel elements having bearing surfaces that are at least partially complementary in the longitudinal chain direction and have sliding surfaces that extend at least over portions thereof as an arc contour, wherein an adjusting force of a drive member oriented transversely to the longitudinal chain direction and configured as a thrust bolt can be introduced into the compression-resistant chain and, when doing so, the chain links can be moved by means of a sprocket wheel into a compression-resistant position and can be returned from this position according to the preamble of claim 1.

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### SUMMARY OF THE INVENTION

The invention solves this problem with a drive chain wherein the thrust bolt engages between the neighboring swivel elements in the area of the arc contours forming partial surfaces of the two bearing surfaces ~~having the features of claim 1.~~ With regard to important additional embodiments, reference is being had to the dependent ~~claims 2 to 8.~~

### **Replacement Page 3, 1st Full Paragraph**

#### **BRIEF DESCRIPTION OF THE DRAWINGS**

Further details and advantageous embodiments of the invention will result from the following description and the drawing in which one embodiment of the drive chain according to the invention is illustrated. The drawings show in:

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### DESCRIPTION OF PREFERRED EMBODIMENTS

In Fig. 1, a drive chain is illustrated that is referenced as a whole by 3; by means of the drive chain an adjusting device in the form of a lifting table or similar working device, referenced generally by 1 in Fig. 3, is movable by continuous adjustment. The drive chain 3 has sequentially arranged chain links 4 that are movable by means of a sprocket wheel 5 driven by motor [[M]] MOT into a compression-resistance lifting position (arrow F', chain links 4').